Computational scientific discovery

Roger Guimerà ICREA & Univ. Rovira i Virgili, Catalonia

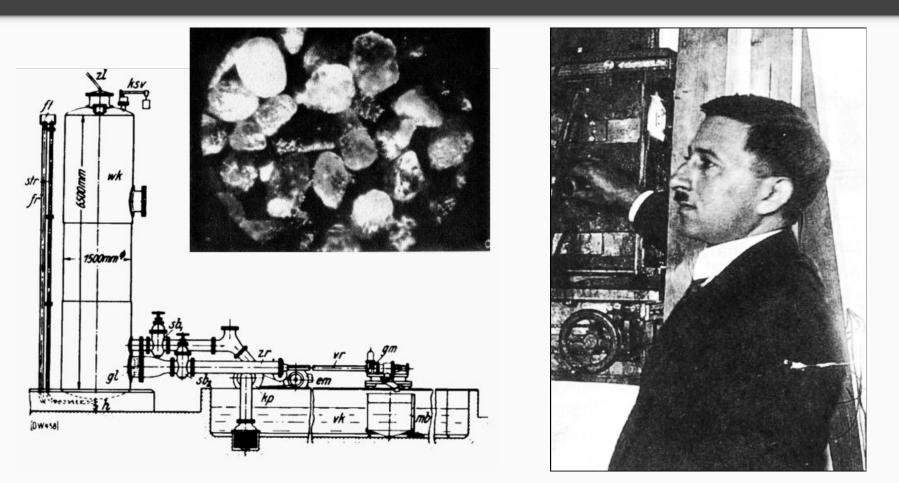
1st SMASH Workshop, Vipava, Slovenia October 10th, 2024



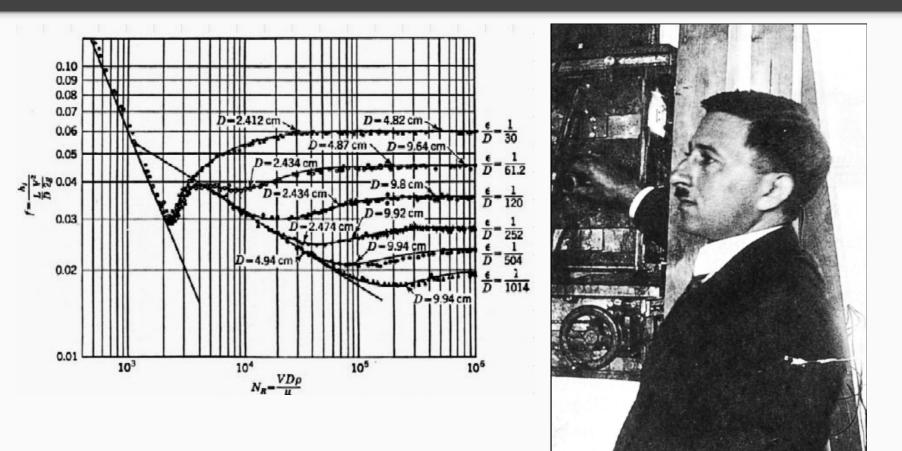


UNIVERSITAT ROVIRA i VIRGILI

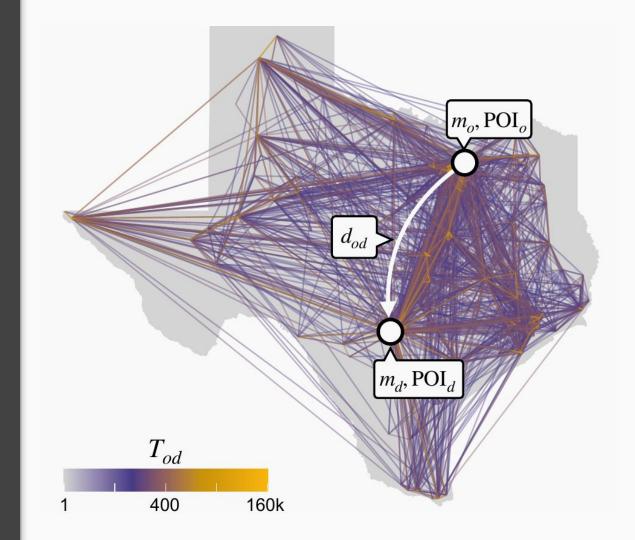
Nikuradse's 1933 experiments about friction in rough pipes



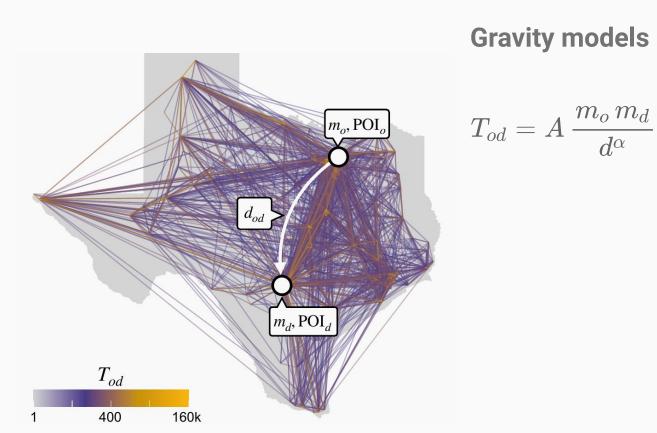
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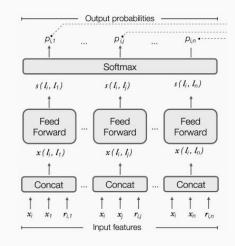
Can we find models that predict human mobility flows?



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"Deep gravity" model



Simini et al., Nature Comm. (2021)



Can we design a "machine scientist" that automates the task of building closed-form mathematical models from data?



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$$f(x)=a_0+a_1x$$
 $f(x)=\log\left(\sin\left(\exp\left(x^{-8}
ight)
ight)
ight)$

Kouzou Sakai / Quanta Magazine

 $EC_1 + C_2 + C_3 M_{i_0} \frac{C_4 + C_5 + C_5}{j \neq i_0}$

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 $F = G^{m_1}$

G(M1+

in

for the machine scientist

It should take arbitrary data as input and produce closed-form, interpretable mathematical models

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It should be able to rigorously and quantitatively **establish the plausibility** of a model given some data

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It should be able to rigorously and quantitatively **establish the plausibility** of a model given some data

It should be able to systematically explore the space of all possible mathematical models, so that the stationary distribution of visited models is (at least asymptotically) given by their plausibility

$y=f(x,\theta)$

p(f | {x, y})

This posterior over expressions *f* encapsulates the full probabilistic solution to the symbolic regression problem

Without parameters:

$$p(M|D) = \frac{p(D|M) p(M)}{p(D)}$$

With parameters:

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With parameters:

$$p(f,\theta|D) = \frac{p(D|f,\theta) p(f,\theta)}{p(D)} = \frac{p(D|f,\theta) p(\theta|f) p(f)}{p(D)}$$
$$p(f|D) = \int_{\Theta} d\theta \ p(f,\theta|D) = \frac{1}{p(D)} \int_{\Theta} d\theta \ p(D|f,\theta) p(\theta|f) p(f)$$

integrated likelihood

The posterior can be rewritten as

$$egin{aligned} p(f|D) &= rac{1}{p(D)} \int_{\Theta} d heta \, p(D|f, heta) \, p(heta|f) \, p(f) \ &= rac{\mathrm{e}^{-\mathcal{L}(f,D)}}{p(D)} \end{aligned}$$

The posterior can be rewritten as

$$\begin{split} p(f|D) &= \frac{1}{p(D)} \int_{\Theta} d\theta \, p(D|f,\theta) \, p(\theta|f) \, p(f) \\ &= \frac{\mathrm{e}^{-\mathcal{L}(f,D)}}{p(D)} \end{split}$$

And the *description length* can be approximated as

$$\mathcal{L}(f,D) = rac{B(f)}{2} - \log p(f)$$
 BIC prior

Dutch book-type argument: Betting on models using any alternative assignment of plausibility results in sets of bets that one would be willing to accept but that result in certain loss

Consistency argument: Any alternative that does not coincide with the probabilistic approach in the large *N* limit will **not** select the true generating model in this limit

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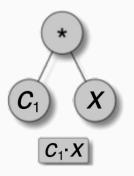
Consistency argument: Any alternative that does not coincide with the probabilistic approach in the large *N* limit will **not** select the true generating model in this limit

for the machine scientist

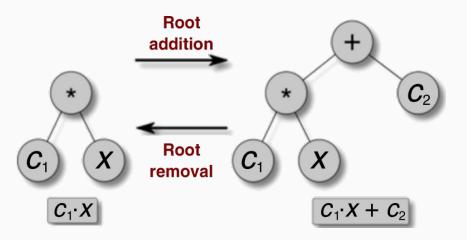
It should take arbitrary data as input and produce closed-form, interpretable mathematical models

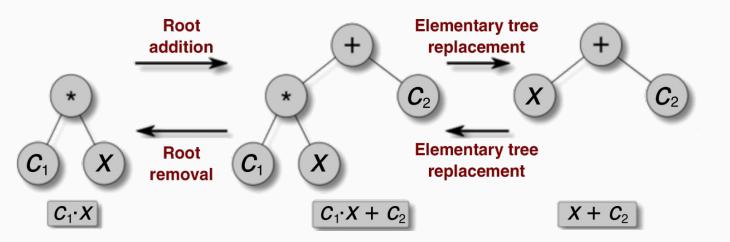
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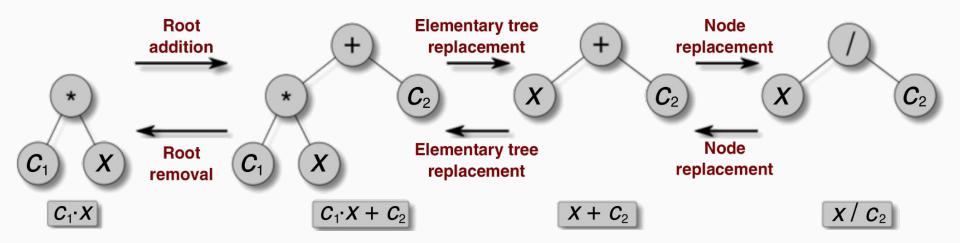
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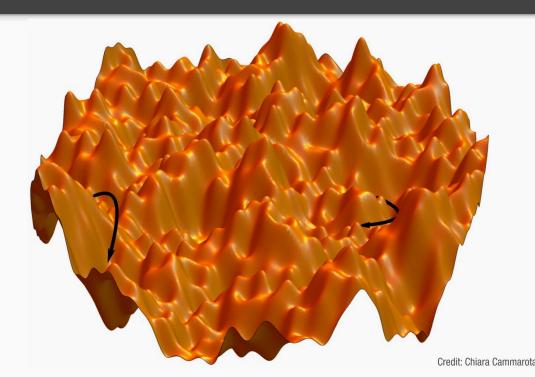
Guimera et al., Science Advances (2020)







Guimera et al., Science Advances (2020)



All in all, we have defined our Bayesian machine scientist

It establishes the plausibility of any model by means of the posterior (i.e. description length) It explores the space of models and samples models from their posterior using Metropolis-Hastings

$$\mathcal{L}(M,D) ~=~ rac{B(M)}{2} - \log p(M)$$

Standard symbolic regression vs Bayesian machine scientist

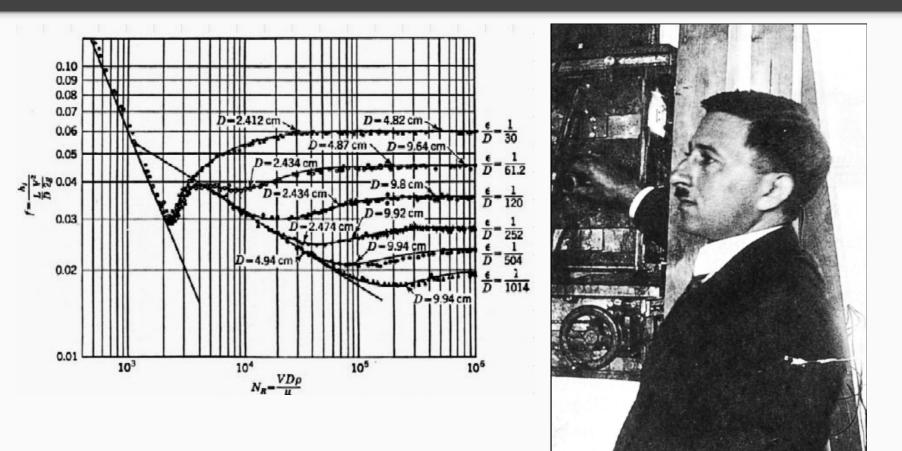
Standard symbolic regression and equation discovery	Bayesian machine scientist
Need to define goodness of fit (or loss) measure	Maximum a posterior (i.e. minimum description length) imposed by probability theory
Need to penalize model complexity heuristically	Need to specify a prior, but at least the assumptions we are making are explicit and transparent
Need to balance goodness of fit and model complexity	Goodness and complexity are balanced automatically
Heuristic exploration of the space of possible models	We sample from the posterior

So, does it work?

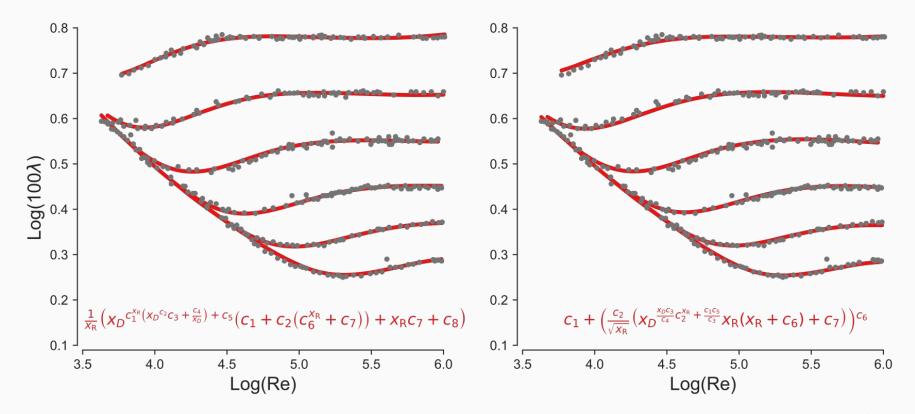
We generate synthetic data and see if the machine scientist is able to recover the correct model



Nikuradse's 1933 experiments about friction in rough pipes

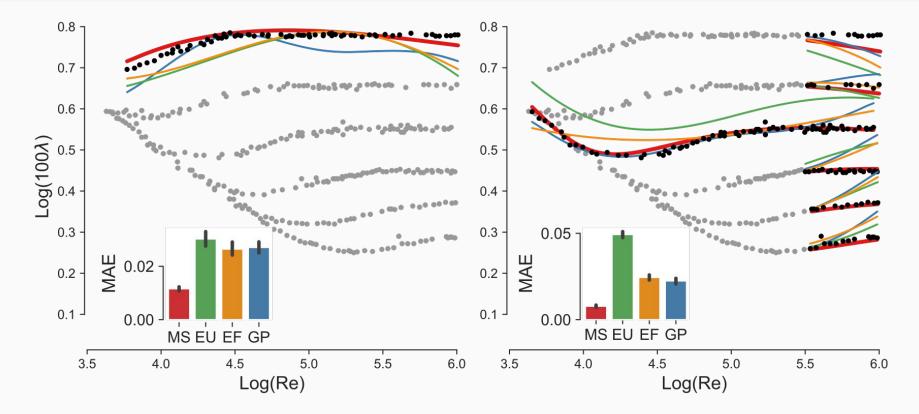


The machine scientist finds multiple expressions that describe the data well



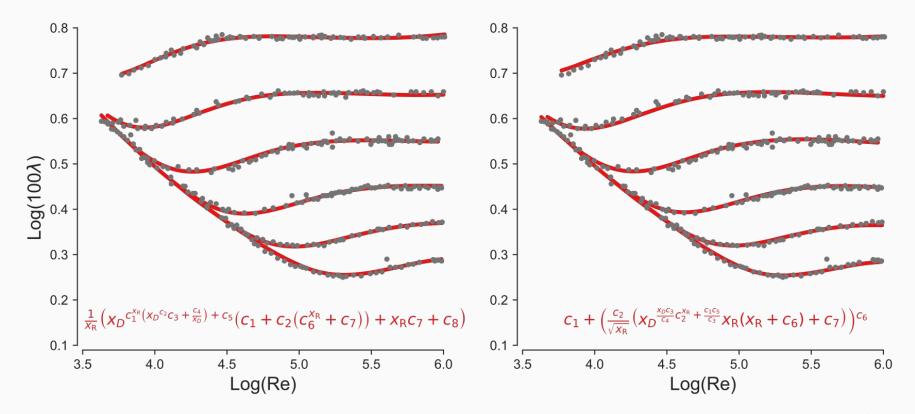
Guimera et al., Science Advances (2020) Reichardt et al., Phys. Rev. Lett (2020)

The machine scientist is also able to make accurate predictions for unobserved data



Guimera et al., Science Advances (2020) Reichardt et al., Phys. Rev. Lett (2020)

The machine scientist finds multiple expressions that describe the data well



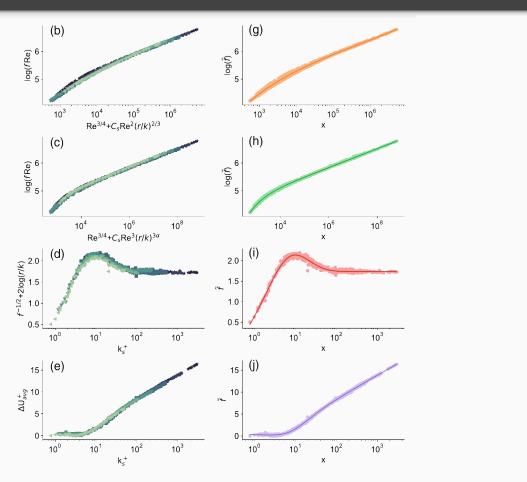
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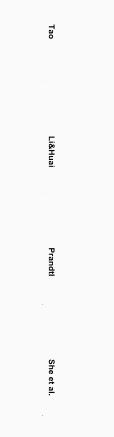
When combined with physical knowledge, the machine scientist provides insight



Reichardt et al., Phys. Rev. Lett (2020)

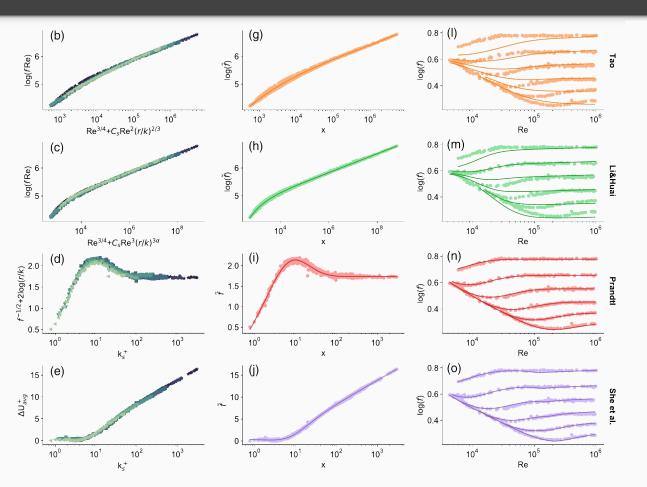
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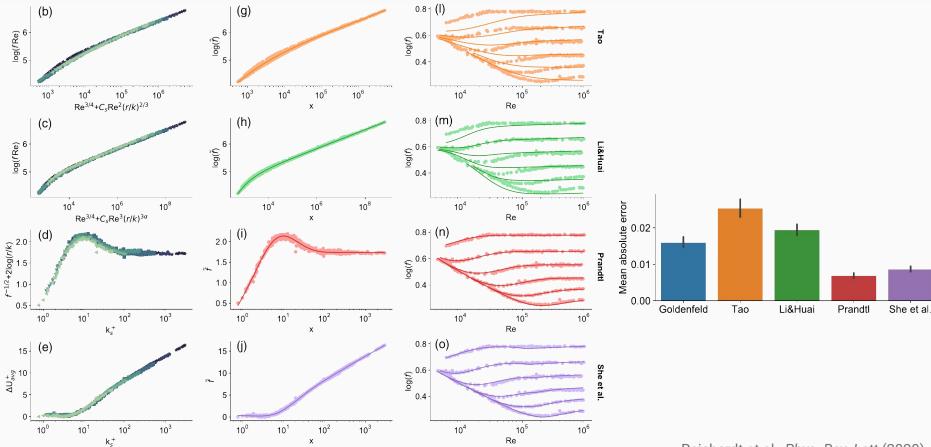
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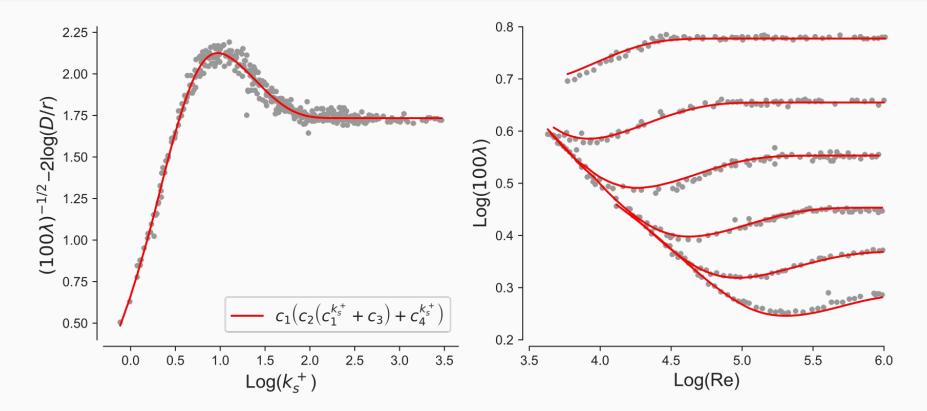
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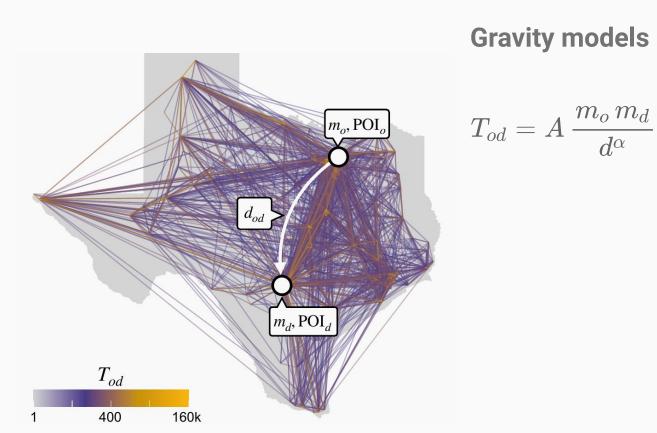
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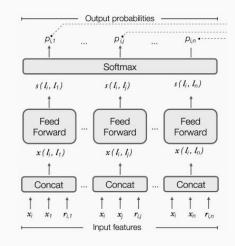


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Can we find models that predict human mobility flows?



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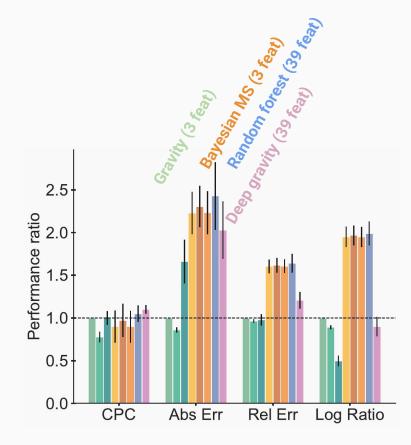
Simini et al., Nature Comm. (2021)

The models identified by the Bayesian machine scientist are gravity-like

$\mathbf{A} \log T_{od} = A \left(1 + \frac{B((m_d + C)(m_o + D))^{\beta}}{d} \right)^{\xi}$													
	Α	B(/10⁻⁰)	C (/10²)	D (/10⁴)	ξ	β							
New York	4.27	441	1.76	1.51	0.26	0.54							
Massachusetts	6.79	9.15	144	11.0	0.28	0.69	3.0 _T	_					
California	21.43	20.2	92.0	34.8	0.50	0.61	0.5	С					
Florida	2.66	6.87	231	2.26	0.33	0.73	2.5 -						
Washington	3.68	17.9	64.2	4.09	0.24	0.69	- 2.0 o						
Texas	4.10	1240	0.612	1.79	0.30	0.50	ants	•					•
							Exponents			•	:	•	
В						0	d X		•			•	
$\log T_{i} = \log \left(A \left(\frac{B(m_d m_o + Cm_d + D)}{1 + 1} + 1 \right)' \right)$							^ш 1.0 -						
$\log I_{od} = \log \left(A \left(d^{\alpha} \right) \right)$					· · · ,))	0.5 -					•	α
	Α	B (/10 ⁻⁹)	C (/10⁴)	D (/10°)	α	Ŷ						•	1/β
New York	86.96	289	1.02	1.03	1.72	0.97	0.0	1					<u> </u>
Massachusetts	68.08	8.50	5.28	27.8	1.17	1.78	N	IY	MA	CA	FL	WA	ТΧ
California	105.7	27.3	2.43	5.90	1.60	2.02							
Florida	58.14	99.2	2.07	4.29	1.49	1.33							
Washington	89.07	33.7	2.47	6.10	1.26	1.41							
Texas	75.94	278	1.85	3.43	1.80	1.16			Cabana	e-Tiranı	م احتما	ubmitte	d (2024)

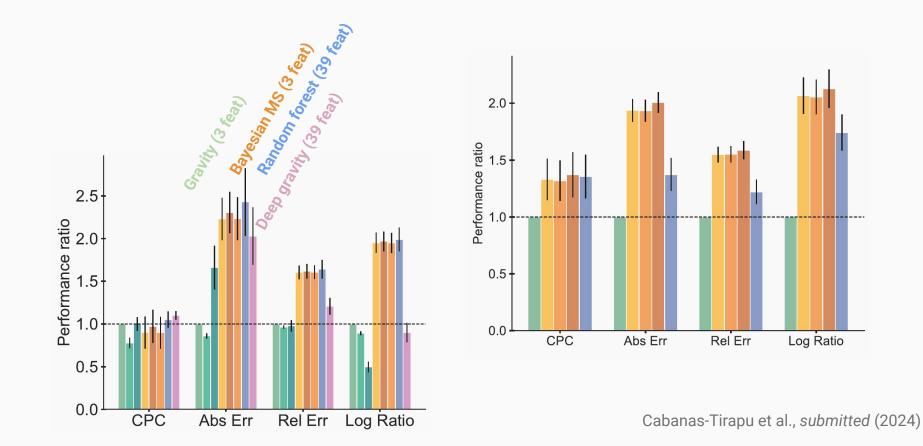
Cabanas-Tirapu et al., submitted (2024)

These gravity-like models are as predictive as "black box" machine learning approaches...



Cabanas-Tirapu et al., submitted (2024)

These gravity-like models are as predictive as "black box" machine learning approaches... and extrapolate significantly better



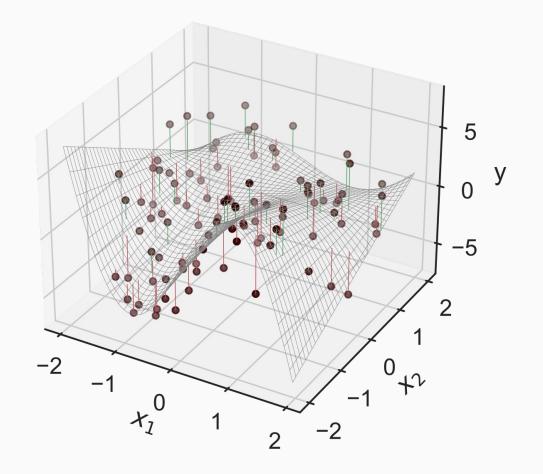
Is it always possible to learn the true generating model?

Intuition

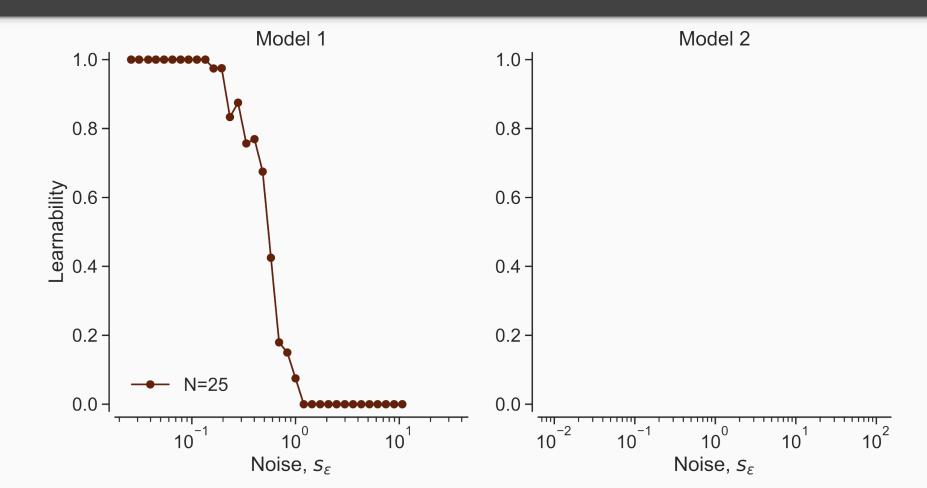
With *enough information*, we should be able to recover the true generating model

But, for a fixed number of points, if the *noise grows*, the true model will eventually become unlearnable

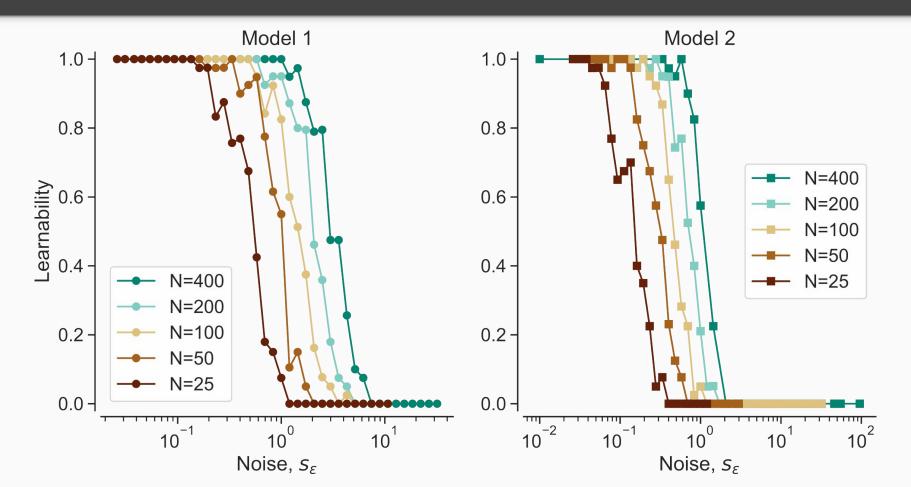
$c_1 x_1 (c_2 + x_2) \cos{(x_1)}$



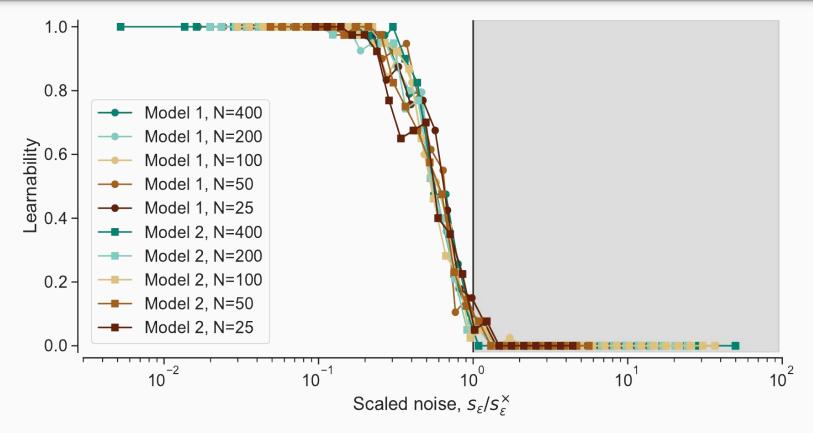
We observe a learnability transition



We observe a learnability transition



Once noise is scaled, all curves collapse: universal behavior?

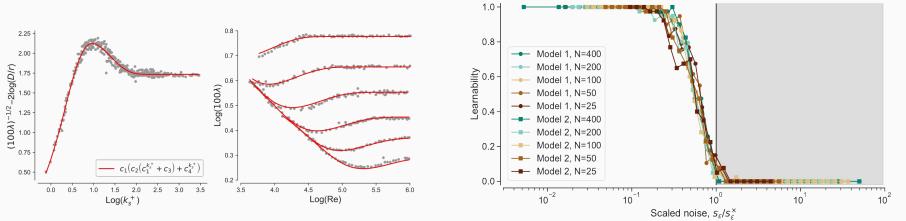


Fajardo-Fontiveros, Reichardt, et al., Nature Comm. (2023)

http://seeslab.info

Conclusions

We can identify closed-form mathematical models from data using a Bayesian approach to symbolic regression... ...but there are fundamental and universal limits to our ability to do so



Thank you

A. Aguilar-Mogas, O. Cabanas-Tirapu, A., H. R. De Los Rios, J. Duch, O. Fajardo-Fontiveros, G. Guillén-Gosálbez, F. A. Massucci, M. Miranda, E. Moro, V. Negri, J. Pallarès, I. Reichardt, **M. Sales-Pardo**, D. Vázquez









Papers:





